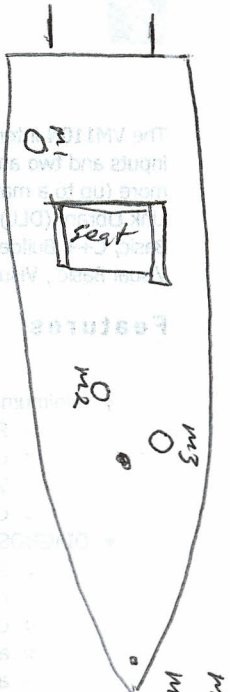


J1 = Rudder
 RT/LT = Rudder
 J2 = main sail / J1b

Laptop
 Notebook
 I pad / phone

Arduino
 motor shield

30 amp
 motor
 controller
 JK133



m1 - Rudder
 m2 - main sail
 m3 - J1b

