

```
void setup() {  
    // put your setup code here, to run once:  
  
    /*  
This code uses the Pulse Sensor Amped by Joel Murphy  
and Yury Gitman  
www.pulsesensor.com  
    >>> Pulse Sensor purple wire goes to Analog Pin 0  
<<<  
Pulse Sensor sample acquisition and processing happens  
in the background via Timer 2 interrupt. 2mS sample  
rate.  
PWM on pins 3 and 11 will not work when using this  
code, because we are using Timer 2!  
The following variables are automatically updated:  
Signal : int that holds the analog signal data  
straight from the sensor. updated every 2mS.  
IBI : int that holds the time interval between  
beats. 2mS resolution.  
BPM : int that holds the heart rate value,  
derived every beat, from averaging previous 10 IBI  
values.  
QS : boolean that is made true whenever Pulse is  
found and BPM is updated. User must reset.  
Pulse : boolean that is true when a heartbeat is  
sensed then false in time with pin13 LED going out.
```

NOTE: This code works with Arduino UNO or Arduino PRO or Arduino Pro Mini 5V or any Arduino running with an ATmega328 and 16MHz clock. This will disable PWM output on pin 3 and 11. Also, it will disable the tone() command.

All the work to find the heartbeat and determine the heartrate happens in the code below.

For using the Pulse Sensor code, see the link below for a code walkthrough:

<http://pulsesensor.myshopify.com/pages/pulse-sensor-amped-arduino-v1dot1>

Code Version 02 by Joel Murphy & Yury Gitman Fall 2012

*/

```
volatile int rate[10];                                // used to
hold last ten IBI values
volatile unsigned long sampleCounter = 0;              // used to determine pulse timing
volatile unsigned long lastBeatTime = 0;                // used to find the inter beat interval
volatile int P =512;                                  // used to
find peak in pulse wave
volatile int T = 512;                                // used to
find trough in pulse wave
volatile int thresh = 512;                            // used to
find instant moment of heart beat
volatile int amp = 100;                             // used to
hold amplitude of pulse waveform
volatile boolean firstBeat = true;                  // used to
seed rate array so we startup with reasonable BPM
volatile boolean secondBeat = true;                 // used to
seed rate array so we startup with reasonable BPM
```

```
void interruptSetup(){
    // Initializes Timer2 to throw an interrupt every
    2mS.
```

```
TCCR2A = 0x02;      // DISABLE PWM ON DIGITAL PINS 3  
AND 11, AND GO INTO CTC MODE  
TCCR2B = 0x06;      // DON'T FORCE COMPARE, 256  
PRESCALER  
    OCR2A = 0X7C;      // SET THE TOP OF THE COUNT TO 124  
FOR 500Hz SAMPLE RATE  
    TIMSK2 = 0x02;      // ENABLE INTERRUPT ON MATCH  
BETWEEN TIMER2 AND OCR2A  
    sei();            // MAKE SURE GLOBAL INTERRUPTS ARE  
ENABLED  
}
```

```
// THIS IS THE TIMER 2 INTERRUPT SERVICE ROUTINE.  
// Timer 2 makes sure that we take a reading every 2  
milliseconds  
ISR(TIMER2_COMPA_vect){          //  
triggered when Timer2 counts to 124  
    cli();                      //  
disable interrupts while we do this  
    Signal = analogRead(pulsePin); // read  
the Pulse Sensor  
    sampleCounter += 2;           // keep  
track of the time in mS with this variable  
    int N = sampleCounter - lastBeatTime; //  
monitor the time since the last beat to avoid noise  
  
// find the peak and trough of the pulse wave  
    if(Signal < thresh && N > (IBI/5)*3){ //  
avoid dichrotic noise by waiting 3/5 of last IBI  
        if (Signal < T){                // T is  
the trough  
            T = Signal;                // keep  
track of lowest point in pulse wave
```

```
        }
    }

    if(Signal > thresh && Signal > P){          // thresh condition helps avoid noise
        P = Signal;                                // P is
the peak
    }                                              // keep
track of highest point in pulse wave

// NOW IT'S TIME TO LOOK FOR THE HEART BEAT
// signal surges up in value every time there is a
pulse
if (N > 250){                                    //
avoid high frequency noise
    if ( (Signal > thresh) && (Pulse == false) && (N >
(IBI/5)*3) ){
        Pulse = true;                            // set
the Pulse flag when we think there is a pulse
        digitalWrite(blinkPin,HIGH);           // turn
on pin 13 LED
        IBI = sampleCounter - lastBeatTime;    // measure time between beats in mS
        lastBeatTime = sampleCounter;           // keep
track of time for next pulse

        if(firstBeat){                         // if
it's the first time we found a beat, if firstBeat ==
TRUE
            firstBeat = false;                 // clear firstBeat flag
            return;                           // IBI
value is unreliable so discard it
    }
}
```

```
        }
        if(secondBeat){ // if
this is the second beat, if secondBeat == TRUE
            secondBeat = false; // 
clear secondBeat flag
            for(int i=0; i<=9; i++){ // seed
the running total to get a realisitic BPM at startup
            rate[i] = IBI;

        }
    }

// keep a running total of the last 10 IBI values
word runningTotal = 0; // clear
the runningTotal variable

for(int i=0; i<=8; i++){ // shift
data in the rate array
            rate[i] = rate[i+1]; // and drop
the oldest IBI value
            runningTotal += rate[i]; // add up
the 9 oldest IBI values
        }

rate[9] = IBI; // add the
latest IBI to the rate array
runningTotal += rate[9]; // add the
latest IBI to runningTotal
runningTotal /= 10; // average
the last 10 IBI values
BPM = 60000/runningTotal; // how many
beats can fit into a minute? that's BPM!
QS = true; // set
```

```

Quantified Self flag
    // QS FLAG IS NOT CLEARED INSIDE THIS ISR
}
}

if (Signal < thresh && Pulse == true){      // when
the values are going down, the beat is over
    digitalWrite(blinkPin,LOW);                // turn
off pin 13 LED
    Pulse = false;                          // reset
the Pulse flag so we can do it again
    amp = P - T;                           // get
amplitude of the pulse wave
    thresh = amp/2 + T;                     // set
thresh at 50% of the amplitude
    P = thresh;                            // reset
these for next time
    T = thresh;
}

if (N > 2500){                                // if 2.5
seconds go by without a beat
    thresh = 512;                            // set
thresh default
    P = 512;                               // set P
default
    T = 512;                               // set T
default
    lastBeatTime = sampleCounter;           // bring
the lastBeatTime up to date
    firstBeat = true;                      // set
these to avoid noise
    secondBeat = true;                     // when we

```

```
get the heartbeat back
}

sei(); // enable
interrupts when you're done!
}// end isr

}

void loop() {
    // put your main code here, to run repeatedly:
```

The pulsesensor.com code needs to be in module
interrupt.ino in the sketch directory

<http://pulsesensor.com/pages/pulse-sensor-amped-arduino-v1dot1>

Code also uses the Adafruit NeoPixel library code
discussed at

<https://learn.adafruit.com/adafruit-neopixel-uberguide>

Version 1.0 by Mike Barela for Adafruit Industries,
Fall 2015

*/

#include <Adafruit_NeoPixel.h> // Library
containing

// Behavior setting variables

```
int pulsePin = 0;                      // Pulse Sensor  
purple wire connected to analog pin 0  
int blinkPin = 13;                     // Digital pin to  
blink led at each beat  
int fadePin  = 5;                      // pin to do fancy  
neopixel effects at each beat  
int fadeRate = 0;                      // used to fade LED  
on with PWM on fadePin  
  
// these variables are volatile because they are used  
during the interrupt service routine  
volatile int BPM;                      // used to hold the  
pulse rate  
volatile int Signal;                   // holds the  
incoming raw data  
volatile int IBI = 600;                 // holds the time  
between beats, the Inter-Beat Interval  
volatile boolean Pulse = false;        // true when pulse  
wave is high, false when it's low  
volatile boolean QS = false;           // becomes true  
when Arduino finds a beat.  
  
// Set up use of NeoPixels  
const int NUMPIXELS = 24;               // Put the number  
of NeoPixels you are using here  
const int BRIGHTNESS = 60;              // Set brightness  
of NeoPixels here  
Adafruit_NeoPixel strip = Adafruit_NeoPixel(NUMPIXELS,  
fadePin, NEO_GRB + NEO_KHZ800);  
  
void setup(){  
    pinMode(blinkPin,OUTPUT);            // pin that will  
    blink to your heartbeat!
```

```
// Serial.begin(115200);           // Serial output
data for debugging or external use
    strip.begin();
    strip.setBrightness(BRIGHTNESS);
    for (int x=0; x < NUMPIXELS; x++) { // Initialize
all pixels to 'off'
        strip.setPixelColor(x, strip.Color(0, 0, 0));
    }
    strip.show();                  // Ensure the
pixels are off
    delay(1000);                 // Wait a second
    interruptSetup();            // sets up to read
Pulse Sensor signal every 2mS
}
```

```
void loop(){
// sendDataSerial('S', Signal);      // send
Processing the raw Pulse Sensor data
    if (QS == true){                // Quantified
Self flag is true when arduino finds a heartbeat
        fadeRate = 255;              // Set 'fadeRate'
Variable to 255 to fade LED with pulse
//     sendDataSerial('B',BPM);      // send heart
rate with a 'B' prefix
//     sendDataSerial('Q',IBI);      // send time
between beats with a 'Q' prefix
        QS = false;                 // reset the
Quantified Self flag for next time
    }
    ledFadeToBeat();                // Routine that
fades color intensity to the beat
    delay(20);                     // take a break
}
```

```
void ledFadeToBeat() {
    fadeRate -= 15;                                // Set LED
    fade value
    fadeRate = constrain(fadeRate,0,255);    // Keep LED
    fade value from going into negative numbers
    setStrip(fadeRate);                           // Write
    the value to the NeoPixels
//    sendDataSerial('R',fadeRate);
}

void sendDataSerial(char symbol, int data ) {
//    Serial.print(symbol);                      // symbol
prefix tells Processing what type of data is coming
//    Serial.println(data);                     // the data
to send culminating in a carriage return
}

void setStrip(int r) {    // Set the strip to one
color intensity (red)
    int g = 0;                            // Green is set to zero (for
non-red colors, change this)
    int b = 0;                            // Blue is set to zero (for
non-red colors, change this)
    for (int x=0; x < NUMPIXELS; x++) {
        strip.setPixelColor(x, strip.Color(r, g, b));
    }
    strip.show();
}

}
```