

```
COM4
Finished Setup Section
Reading incoming data: 13
Reading incoming data: 10

Reading incoming data: 79 0
Reading incoming data: 75 K
Reading incoming data: 13
Reading incoming data: 10

Reading incoming data: 13
Reading incoming data: 10

Reading incoming data: 79 0
Reading incoming data: 75 K
Reading incoming data: 13
Reading incoming data: 10

Reading incoming data: 13
Reading incoming data: 10

Reading incoming data: 43 +
Reading incoming data: 67 C
Reading incoming data: 77 M
Reading incoming data: 84 T
Reading incoming data: 58 :
Reading incoming data: 32
Reading incoming data: 34 "
Reading incoming data: 43 +
Reading incoming data: 50 2
Reading incoming data: 55 7
Reading incoming data: 55 7
Reading incoming data: 50 2
Reading incoming data: 53 5
Reading incoming data: 49 1
Reading incoming data: 51 3
Reading incoming data: 56 8
Reading incoming data: 54 6
Reading incoming data: 54 6
Reading incoming data: 56 8
Reading incoming data: 34 "
Reading incoming data: 44 ,
Reading incoming data: 34 "
Reading incoming data: 34 "
Reading incoming data: 44 ,
Reading incoming data: 34 "
```

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COM4
Reading incoming data: 34 "
Reading incoming data: 44 ,
Reading incoming data: 34 "
Reading incoming data: 34 "
Reading incoming data: 44 ,
Reading incoming data: 34 "
Reading incoming data: 49 1
Reading incoming data: 52 4
Reading incoming data: 47 /
Reading incoming data: 49 1
Reading incoming data: 49 1
Reading incoming data: 47 /
Reading incoming data: 48 0
Reading incoming data: 54 6
Reading incoming data: 44 ,
Reading incoming data: 49 1
Reading incoming data: 55 7
Reading incoming data: 58 :
Reading incoming data: 48 0
Reading incoming data: 57 9
Reading incoming data: 58 :
Reading incoming data: 52 4
Reading incoming data: 48 0
Reading incoming data: 43 +
Reading incoming data: 48 0
Reading incoming data: 56 8
Reading incoming data: 34 "
Reading incoming data: 13
Reading incoming data: 10

Reading incoming data: 63 ?
Got a ?
Reading incoming data in loop: Buffer_pos = 0 50 2
Reading incoming data in loop: Buffer_pos = 1 48 0
Reading incoming data in loop: Buffer_pos = 2 33 !
Reading incoming data in loop: Buffer_pos = 3 52 4
Reading incoming data in loop: Buffer_pos = 4 35 #
Reading incoming data in loop: Buffer_pos = 5 97 a
Reading incoming data in loop: Buffer_pos = 6 49 1
2014/11/06
It's a match!
LED status = 1
Message sent
Reading incoming data in loop: Buffer_pos = 0 13
Reading incoming data in loop: Buffer_pos = 1 10
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COM4
Reading incoming data in loop: Buffer_pos = 1 10
Reading incoming data in loop: Buffer_pos = 2 13
Reading incoming data in loop: Buffer_pos = 3 10
Reading incoming data in loop: Buffer_pos = 4 62 >
Reading incoming data in loop: Buffer_pos = 5 32
Reading incoming data in loop: Buffer_pos = 6 13
>
Reading incoming data in loop: Buffer_pos = 0 10
Reading incoming data in loop: Buffer_pos = 1 62 >
Reading incoming data in loop: Buffer_pos = 2 32
Reading incoming data in loop: Buffer_pos = 3 13
Reading incoming data in loop: Buffer_pos = 4 10
Reading incoming data in loop: Buffer_pos = 5 43 +
Reading incoming data in loop: Buffer_pos = 6 67 C
>
+C
Reading incoming data in loop: Buffer_pos = 0 77 M
Reading incoming data in loop: Buffer_pos = 1 71 G
Reading incoming data in loop: Buffer_pos = 2 83 S
Reading incoming data in loop: Buffer_pos = 3 58 :
Reading incoming data in loop: Buffer_pos = 4 32
Reading incoming data in loop: Buffer_pos = 5 54 6
Reading incoming data in loop: Buffer_pos = 6 53 S
MSG: 65
Reading incoming data in loop: Buffer_pos = 0 13
Reading incoming data in loop: Buffer_pos = 1 10
Reading incoming data in loop: Buffer_pos = 2 13
Reading incoming data in loop: Buffer_pos = 3 10
Reading incoming data in loop: Buffer_pos = 4 79 O
Reading incoming data in loop: Buffer_pos = 5 75 K
Reading incoming data in loop: Buffer_pos = 6 13
OK
Reading incoming data in loop: Buffer_pos = 0 10
```

Autoscroll Both NL & CR 19200 baud

05:11 PM 2014/11/06