

```
COM4
Reading incoming data: 79 0
Reading incoming data: 75 K
Reading incoming data: 13
Reading incoming data: 10

Reading incoming data: 13
Reading incoming data: 10

Reading incoming data: 43 +
Reading incoming data: 67 C
Reading incoming data: 77 M
Reading incoming data: 84 T
Reading incoming data: 58 :
Reading incoming data: 32
Reading incoming data: 34 "
Reading incoming data: 43 +
Reading incoming data: 50 2
Reading incoming data: 55 7
Reading incoming data: 55 7
Reading incoming data: 50 2
Reading incoming data: 53 5
Reading incoming data: 49 1
Reading incoming data: 51 3
Reading incoming data: 56 8
Reading incoming data: 54 6
Reading incoming data: 54 6
Reading incoming data: 56 8
Reading incoming data: 34 "
Reading incoming data: 44 ,
Reading incoming data: 34 "
Reading incoming data: 34 "
Reading incoming data: 44 ,
Reading incoming data: 34 "
Reading incoming data: 49 1
Reading incoming data: 52 4
Reading incoming data: 47 /
Reading incoming data: 49 1
Reading incoming data: 49 1
Reading incoming data: 47 /
Reading incoming data: 48 0
Reading incoming data: 54 6
Reading incoming data: 44 ,
Reading incoming data: 49 1
Reading incoming data: 50 2
Reading incoming data: 58 :
...
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COM4
Reading incoming data: 50 2
Reading incoming data: 58 :
Reading incoming data: 49 1
Reading incoming data: 57 9
Reading incoming data: 58 :
Reading incoming data: 51 3
Reading incoming data: 48 0
Reading incoming data: 43 +
Reading incoming data: 48 0
Reading incoming data: 56 8
Reading incoming data: 34 "
Reading incoming data: 13
Reading incoming data: 10

Reading incoming data: 63 ?
Got a ?
Reading incoming data in loop: Buffer_pos = 0 50 2
Reading incoming data in loop: Buffer_pos = 1 48 0
Reading incoming data in loop: Buffer_pos = 2 33 !
Reading incoming data in loop: Buffer_pos = 3 52 4
Reading incoming data in loop: Buffer_pos = 4 35 #
Reading incoming data in loop: Buffer_pos = 5 97 a
Reading incoming data in loop: Buffer_pos = 6 49 1
20!4#s1
It's a match!
LED status = 1
Message sent
Reading incoming data in loop: Buffer_pos = 0 13
Reading incoming data in loop: Buffer_pos = 1 10

Reading incoming data in loop: Buffer_pos = 2 65 A
Reading incoming data in loop: Buffer_pos = 3 84 T
Reading incoming data in loop: Buffer_pos = 4 32
Reading incoming data in loop: Buffer_pos = 5 43 +
Reading incoming data in loop: Buffer_pos = 6 32

AT +
Reading incoming data in loop: Buffer_pos = 0 67 C
Reading incoming data in loop: Buffer_pos = 1 77 M
Reading incoming data in loop: Buffer_pos = 2 71 0
Reading incoming data in loop: Buffer_pos = 3 83 S
Reading incoming data in loop: Buffer_pos = 4 32
Reading incoming data in loop: Buffer_pos = 5 61 =
Reading incoming data in loop: Buffer_pos = 6 32
CMGS =
```

